

Fig. 1

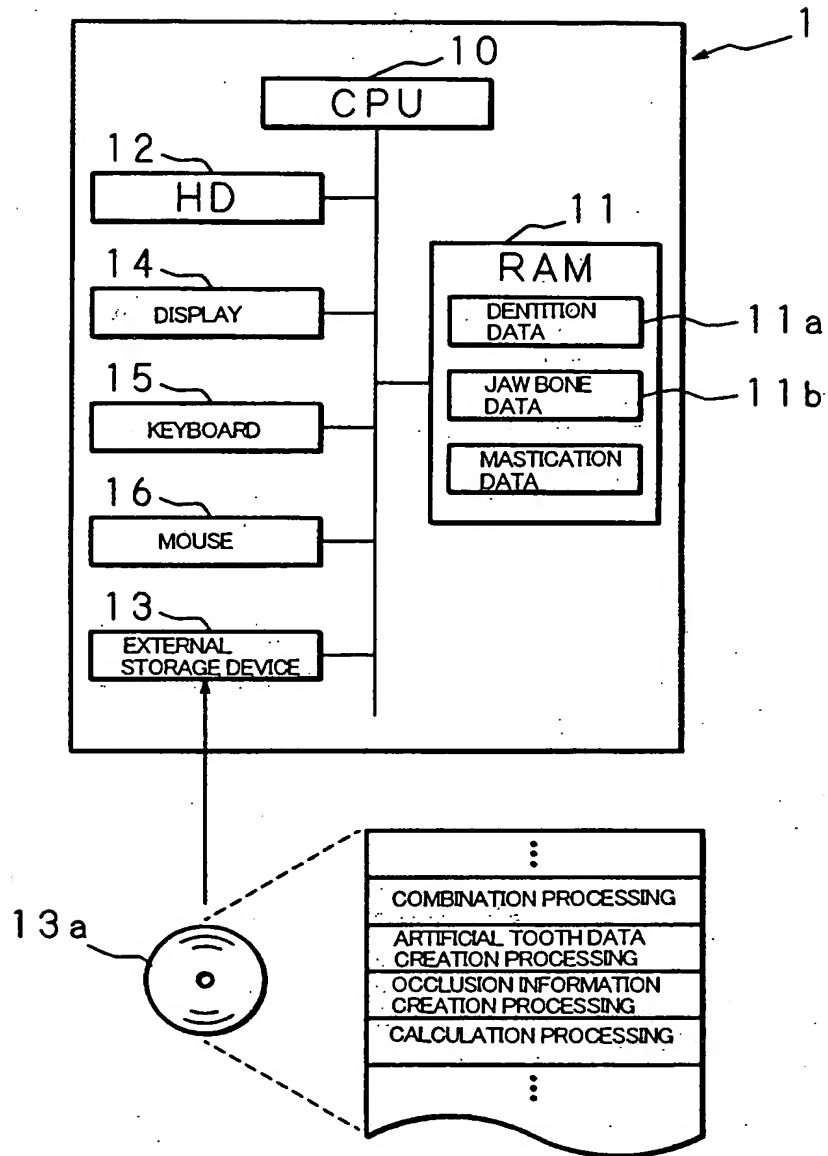
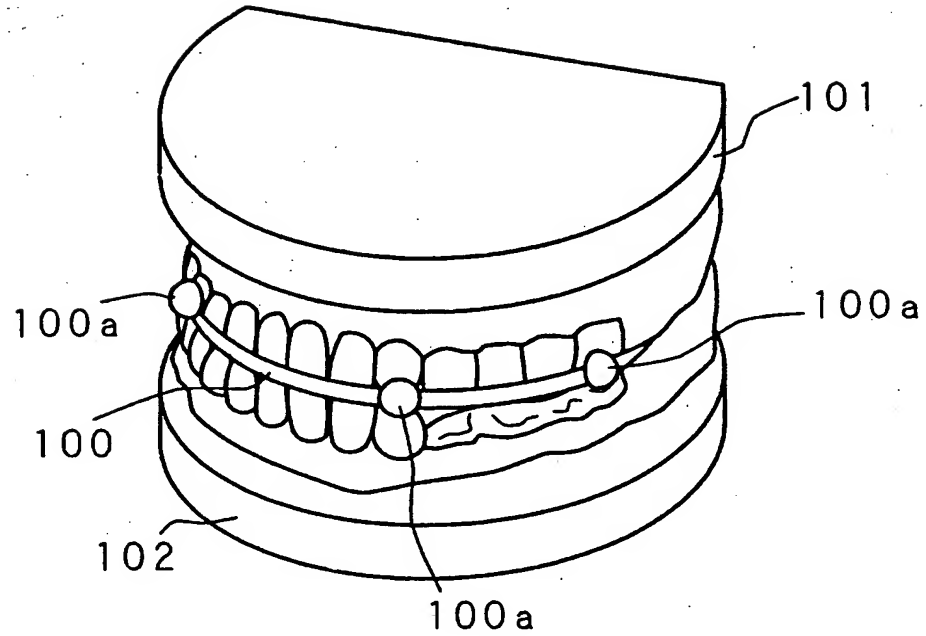


Fig. 2

A



B

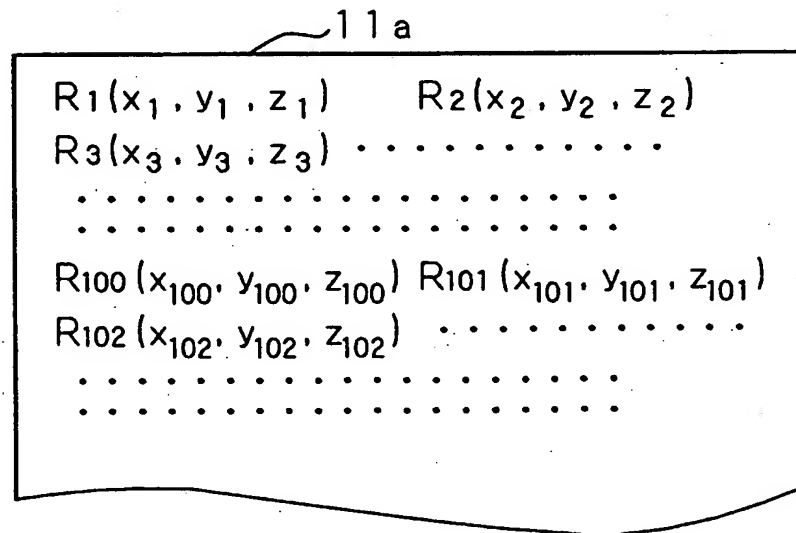
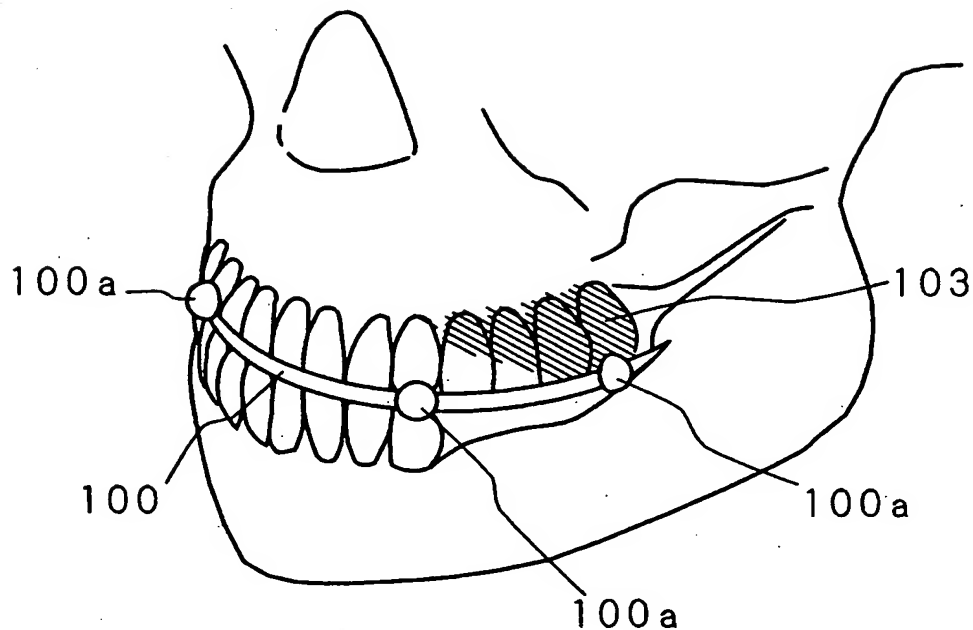


Fig. 3.

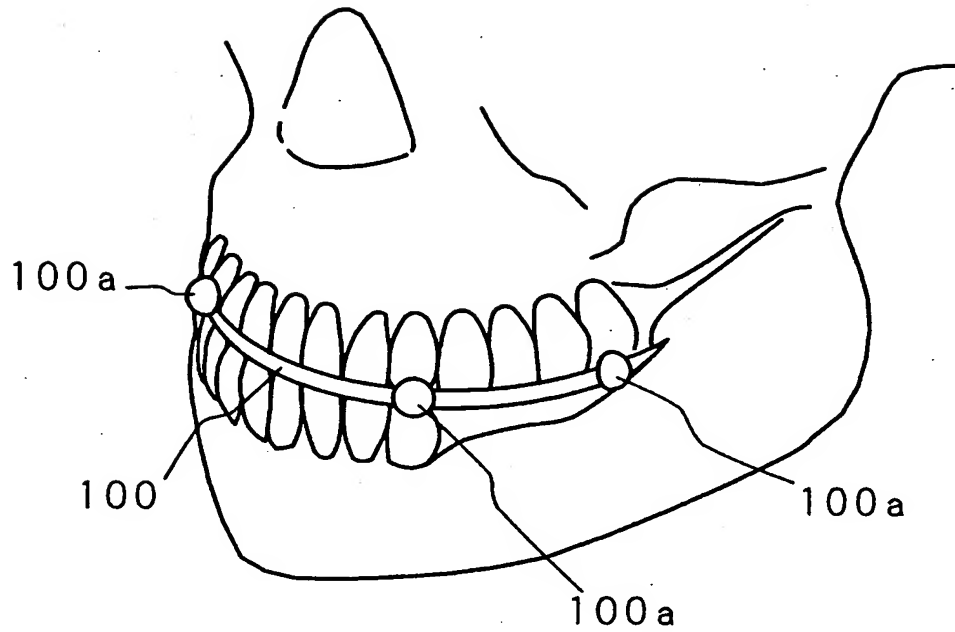
A



B

11b

$J_1(x_1, y_1, z_1, CT_1)$	$J_2(x_2, y_2, z_2, CT_2)$
$J_3(x_3, y_3, z_3, CT_3)$	.....
.....	.....
$J_{200}(x_{200}, y_{200}, z_{200}, CT_{200})$	$J_{201}(x_{201}, y_{201}, z_{201}, CT_{201})$
.....	.....

*Fig. 4**A**B*

$$\begin{array}{l}
 J_1(x_1, y_1, z_1, CT_1) \quad J_2(x_2, y_2, z_2, CT_2) \\
 J_3(x_3, y_3, z_3, CT_3) \quad \dots\dots\dots \\
 \dots\dots\dots \\
 R_1(x_1, y_1, z_1) \quad R_2(x_2, y_2, z_2) \\
 R_3(x_3, y_3, z_3) \quad \dots\dots\dots \\
 \dots\dots\dots
 \end{array}$$

Fig. 5

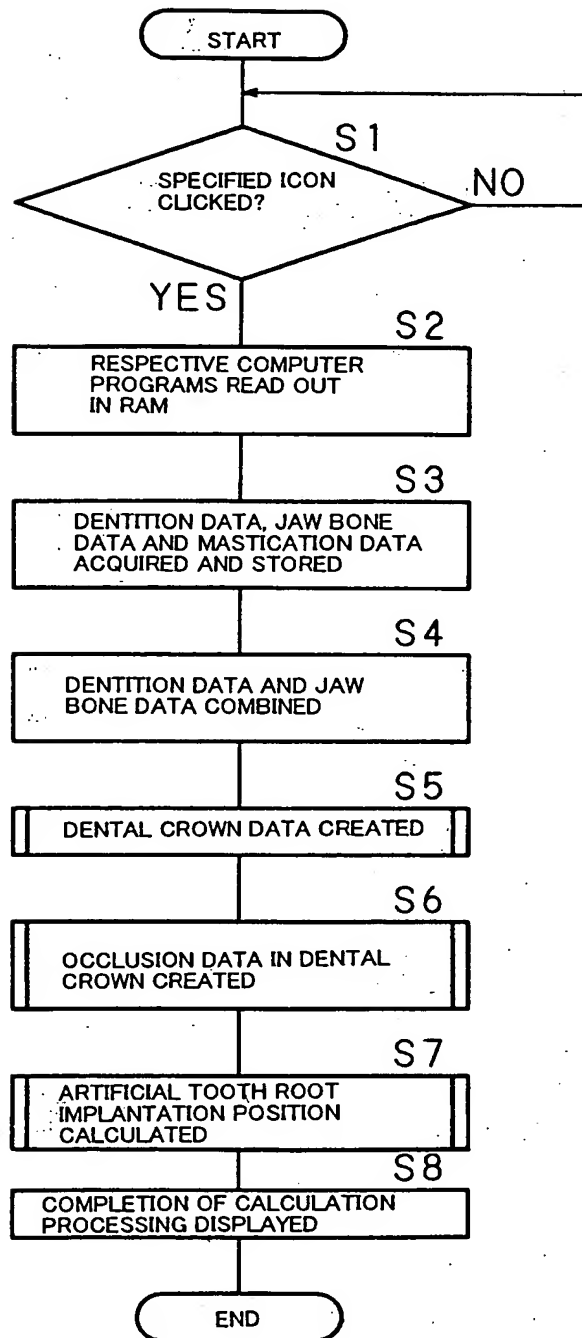


Fig. 6

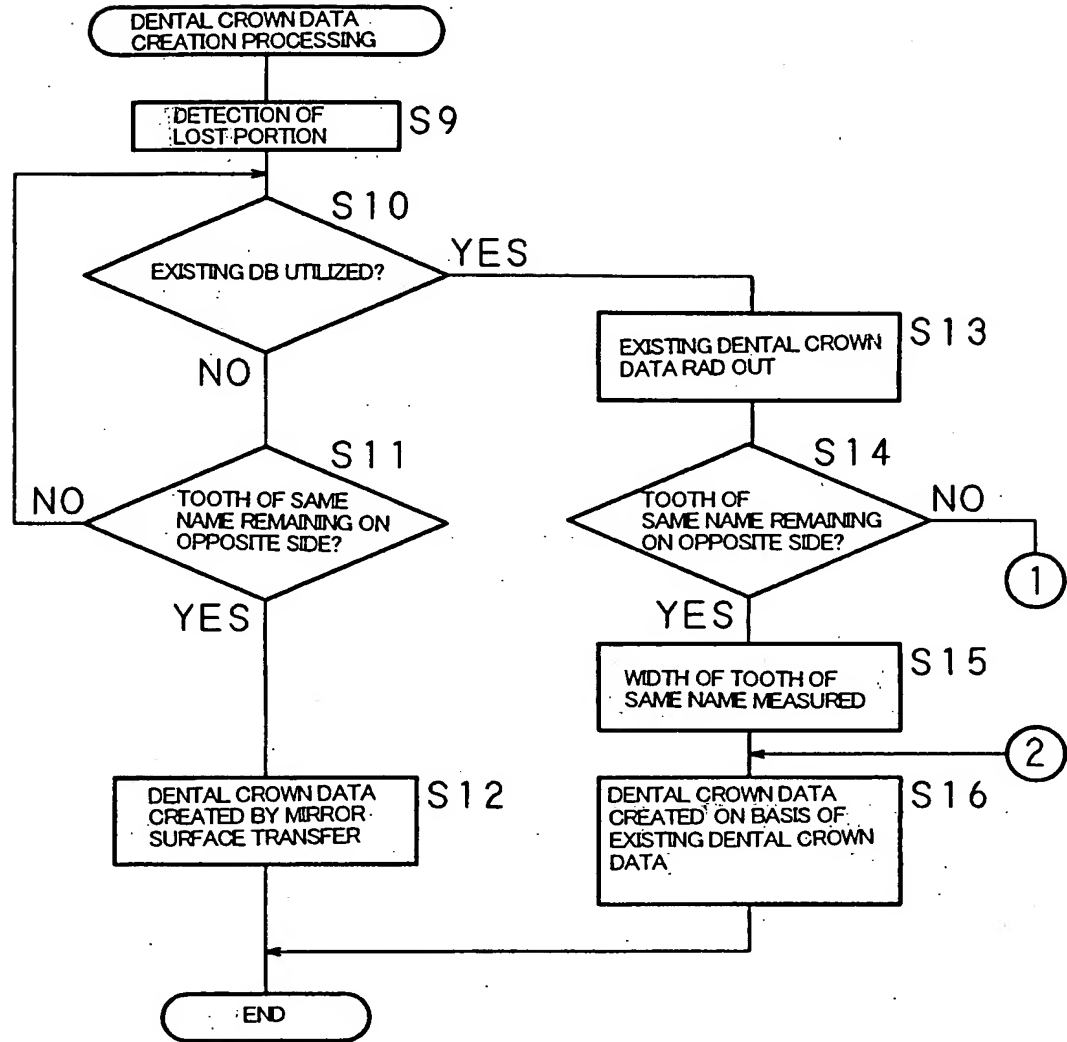


Fig. 7

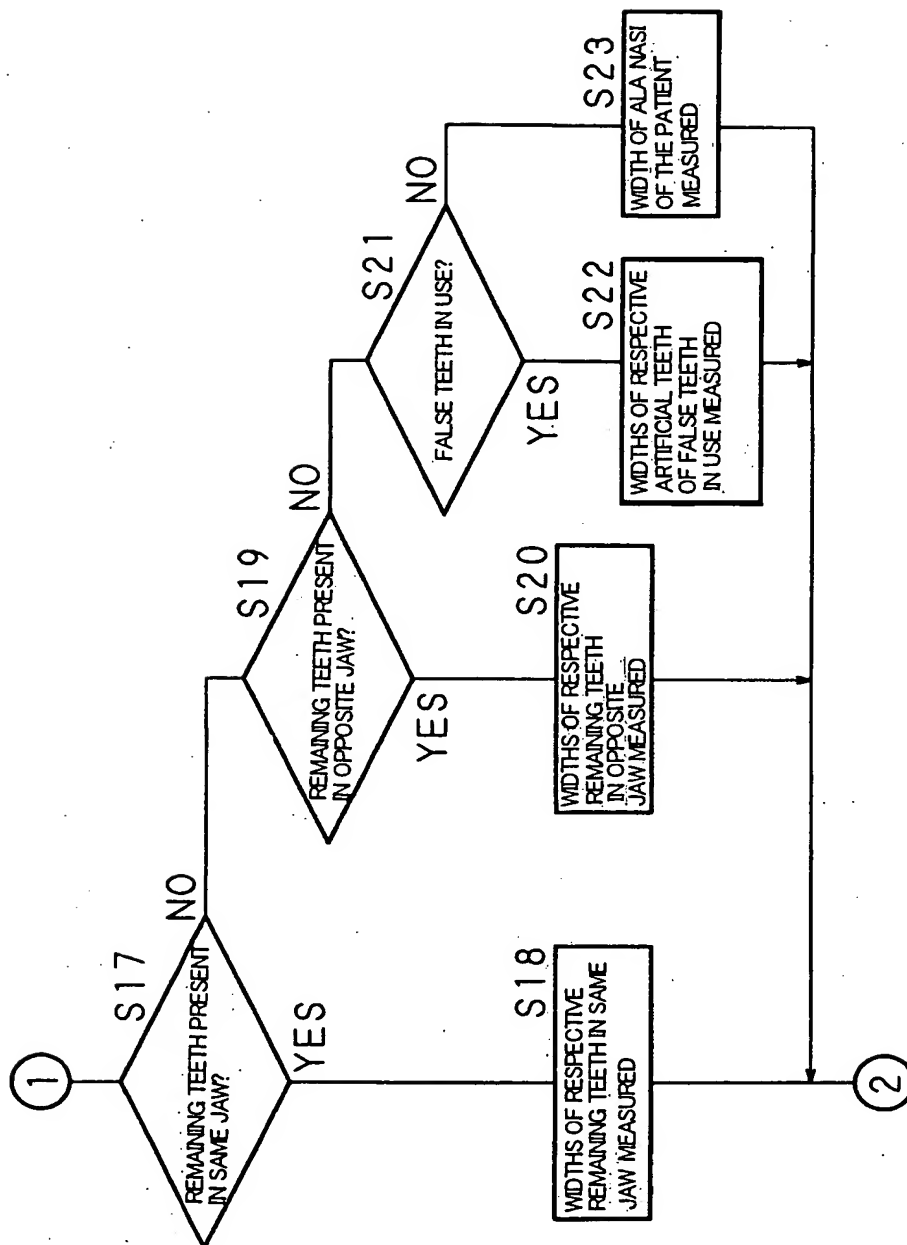


Fig. 8

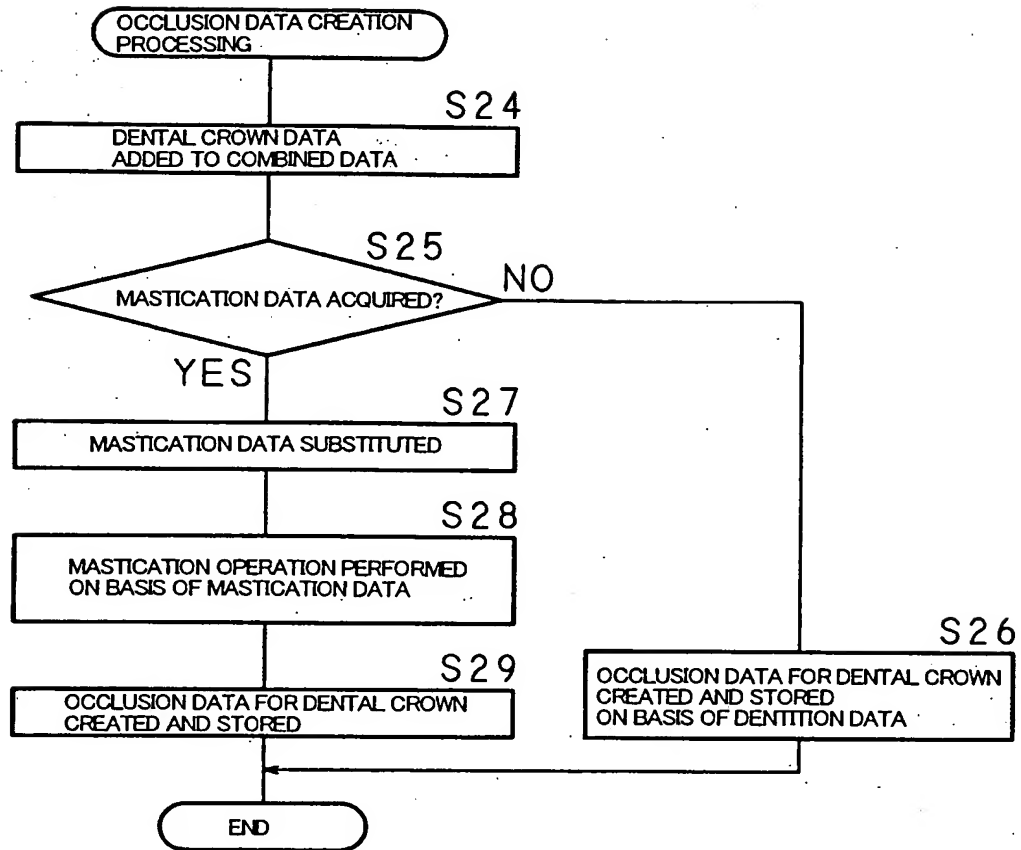




Fig. 9

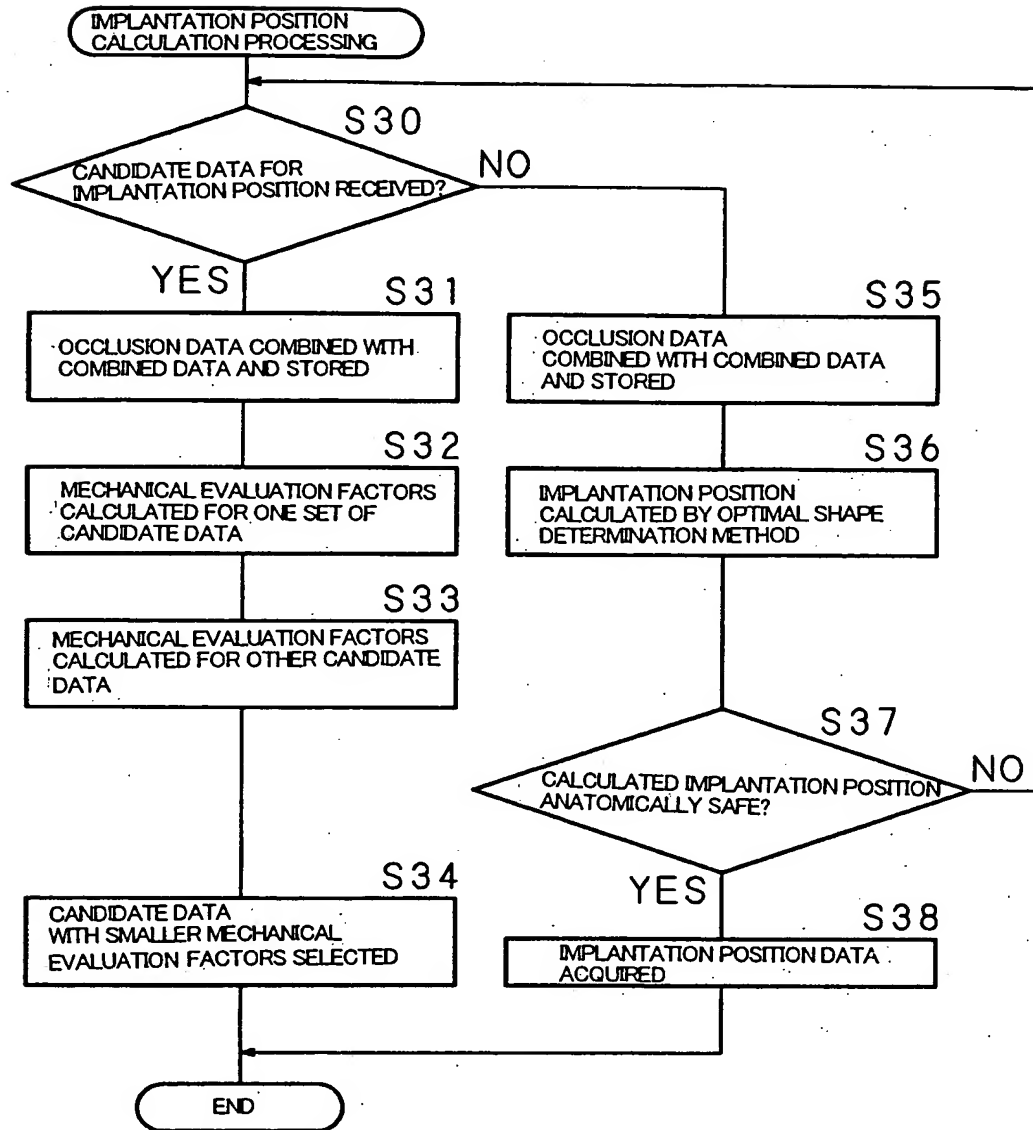


Fig. 10

2

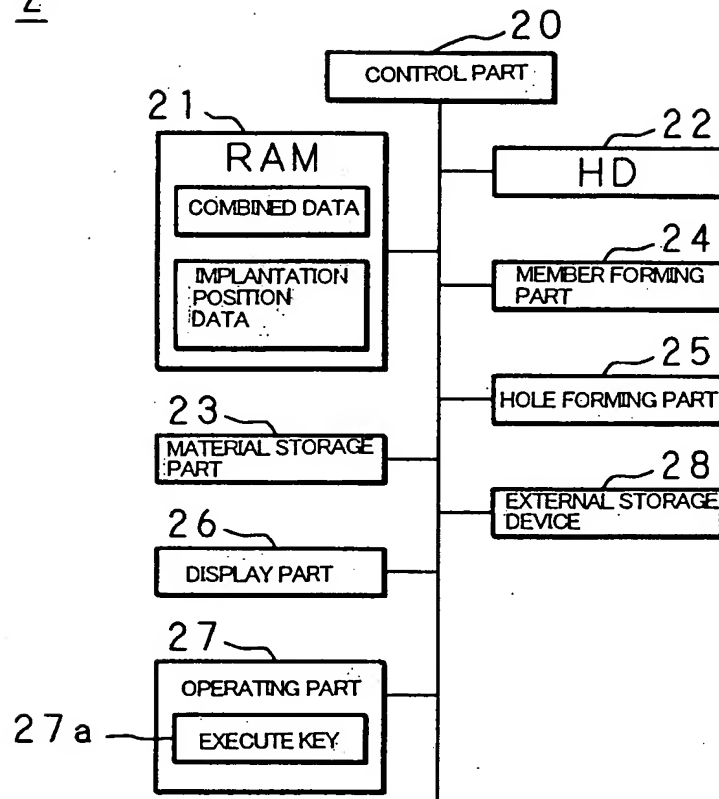
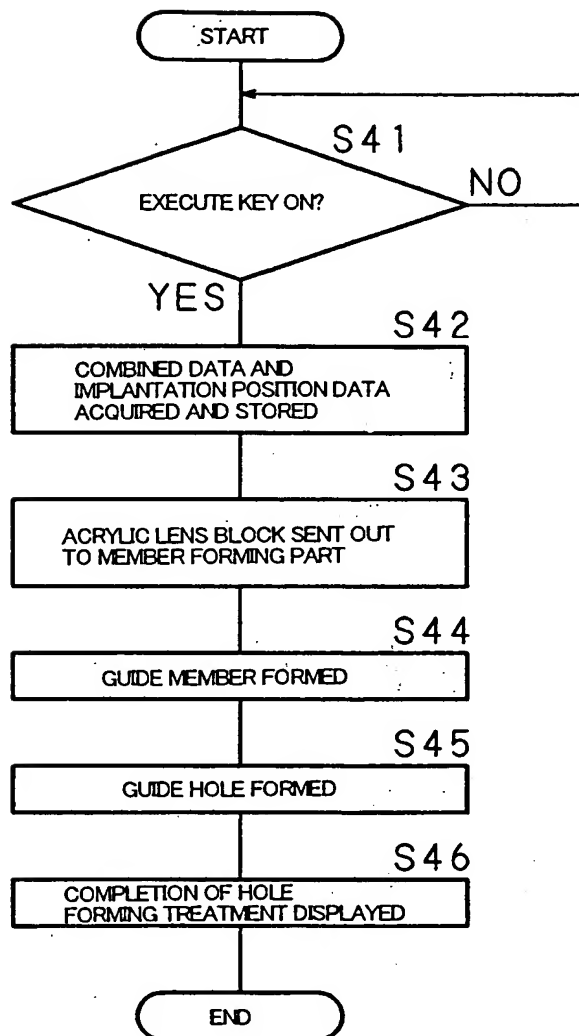


Fig. 11



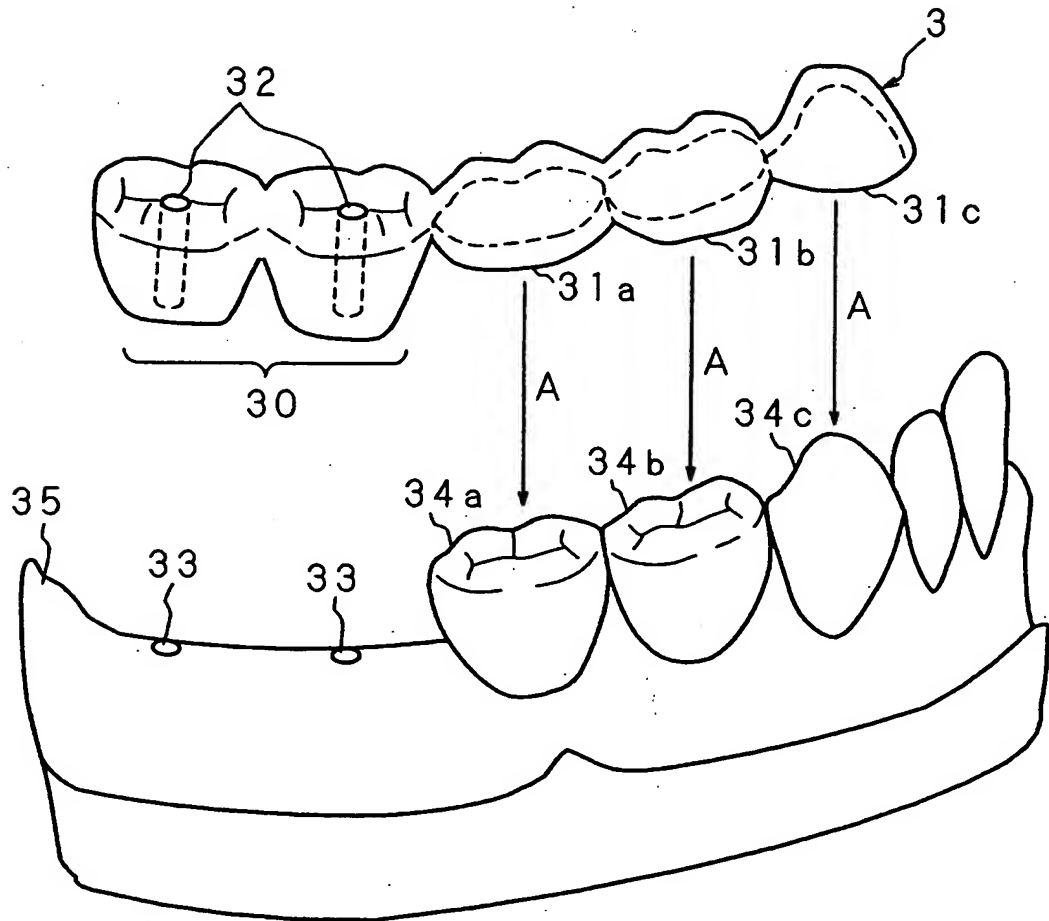
*Fig. 12*

Fig. 13

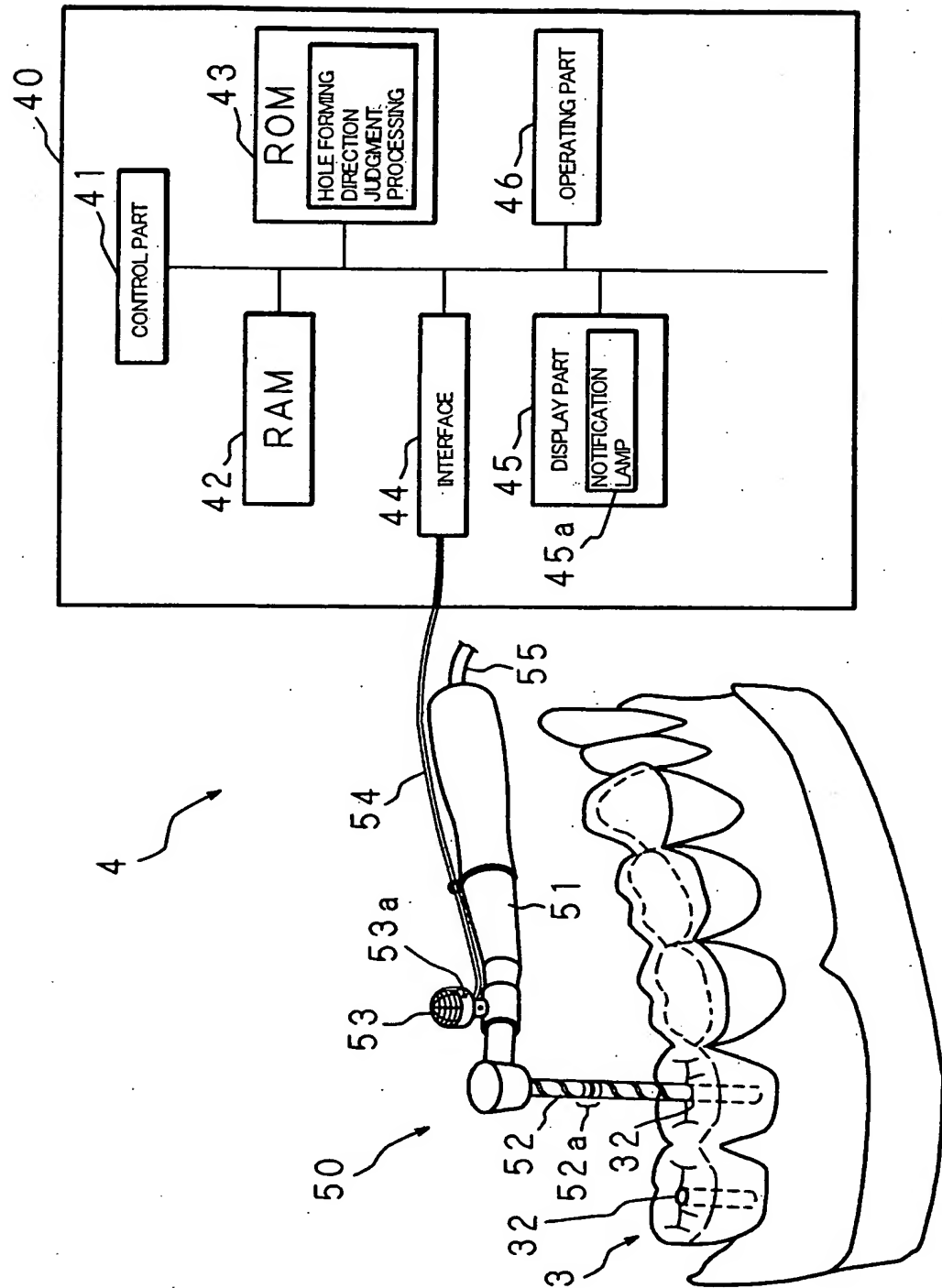


Fig. 14

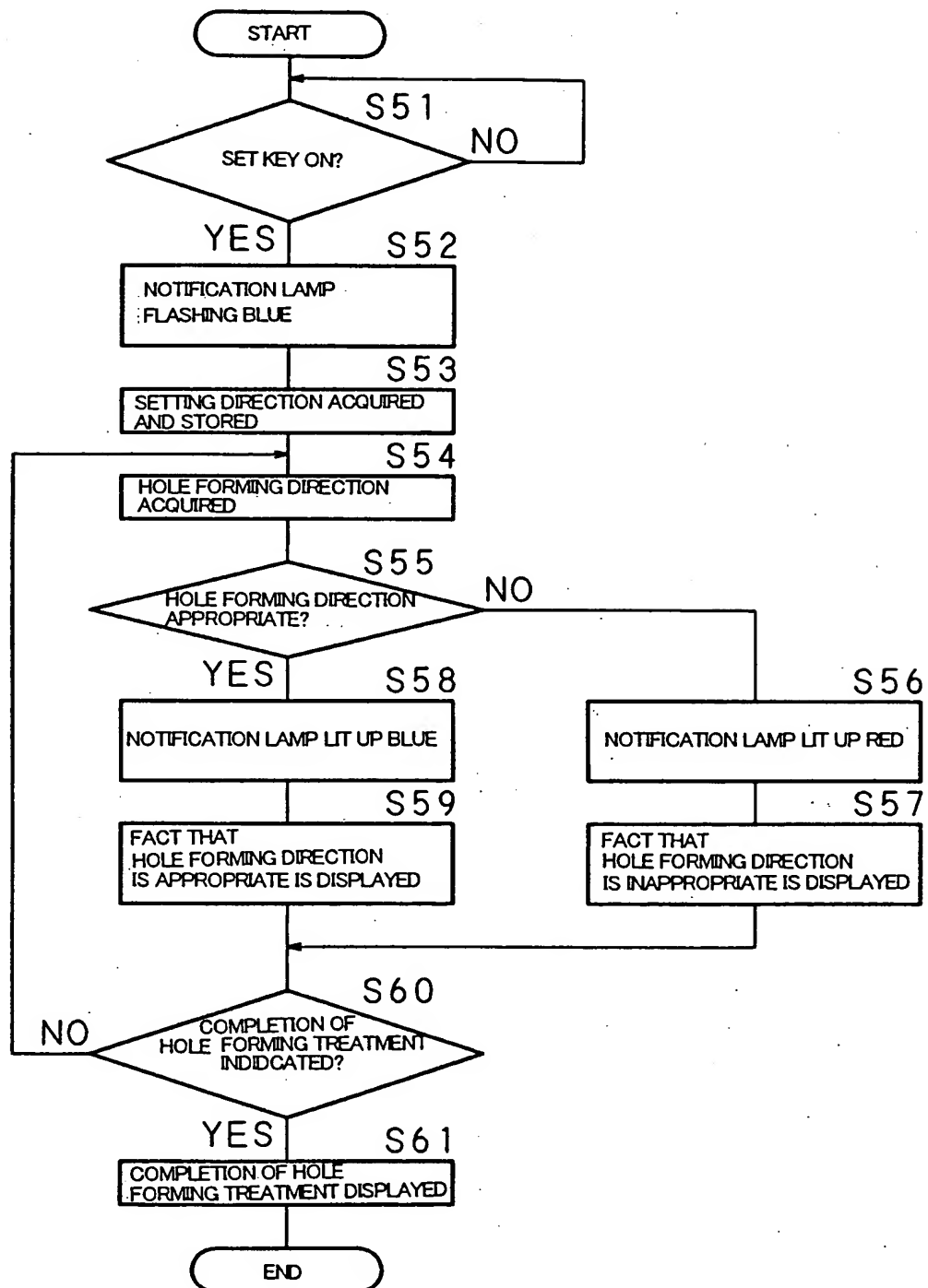


Fig. 15

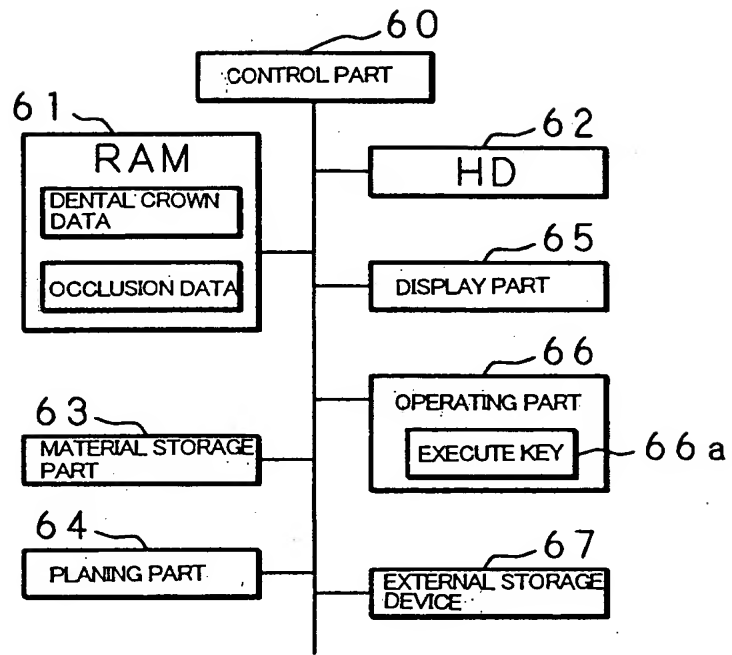
6

Fig. 16

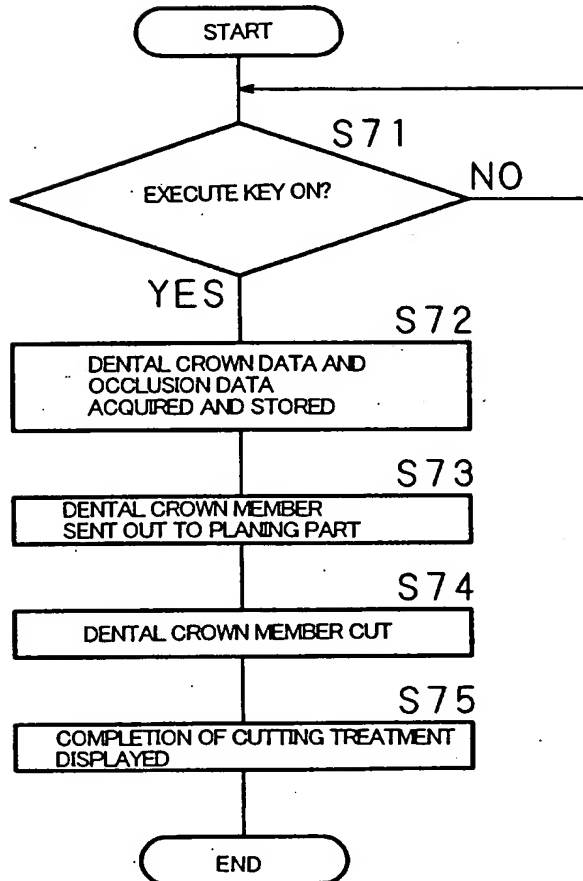




Fig. 17

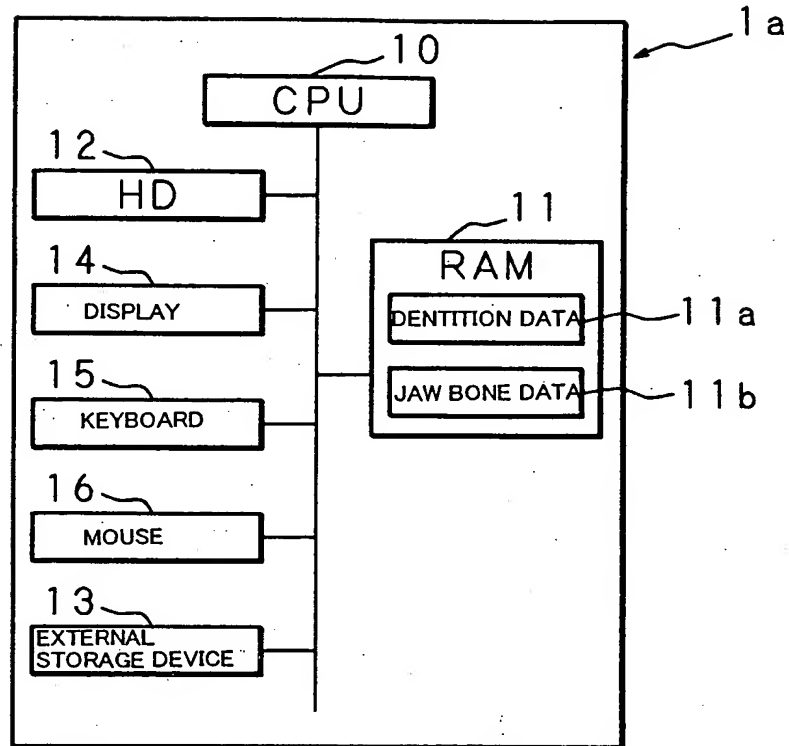
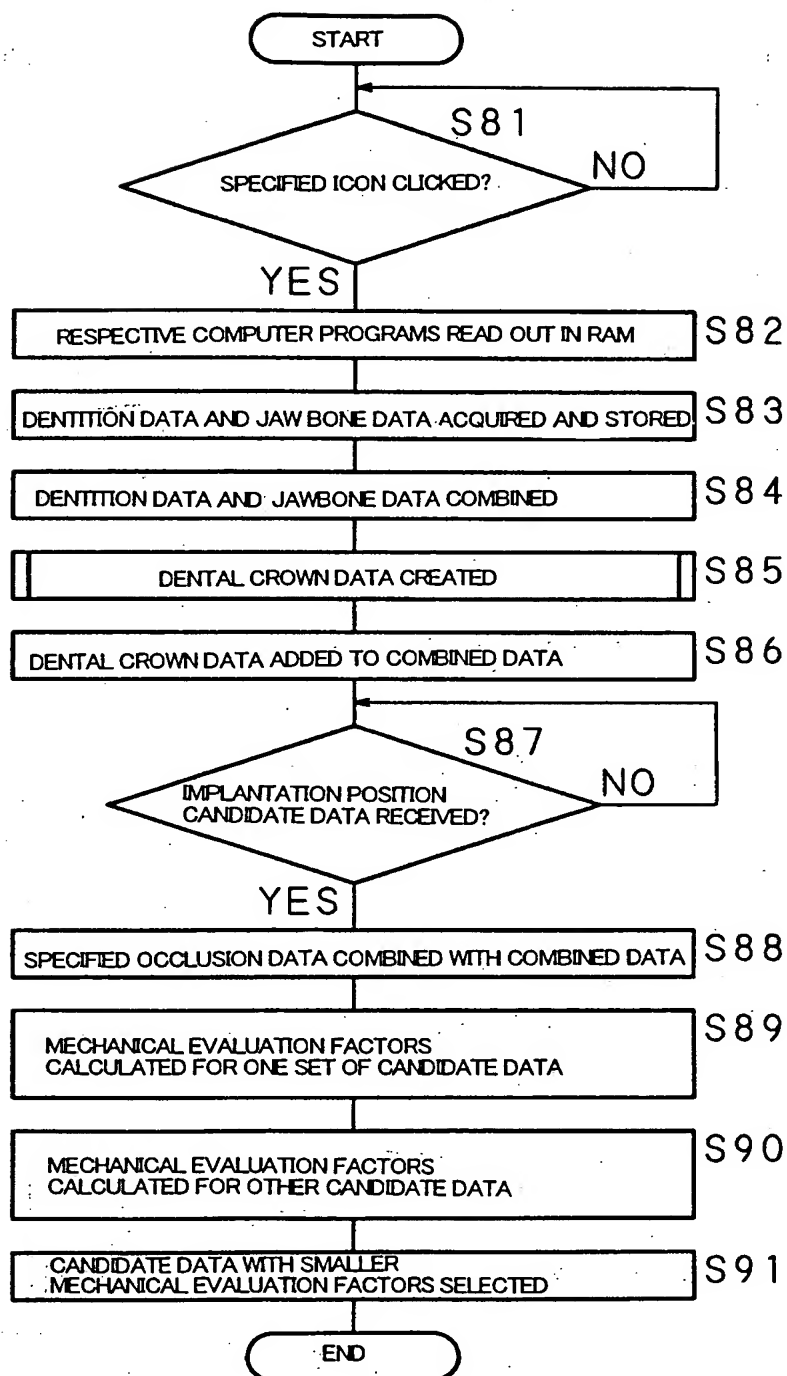
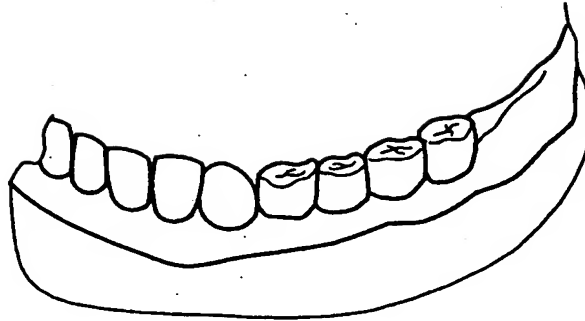
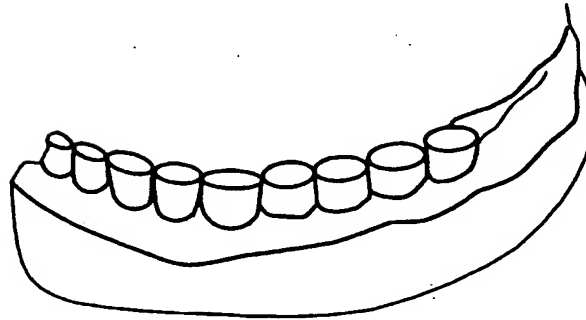


Fig. 18



*Fig. 19**A**B**C*